

14) Appendix III: Spherical Vector Field Solutions

1. Spherical vector field solutions

From the characteristic solutions of the scalar wave equation $\nabla^2 \psi + k^2 \psi = 0$ in spherical coordinates

$$f_{\text{term}} = \cos m\varphi P_n^m(\cos\theta) y_n(kr) \quad f_{\text{term}} = \sin m\varphi P_n^m(\cos\theta) y_n(kr)$$

we can build vector field solutions of the equation $\vec{\nabla}(\vec{\nabla} \cdot \vec{C}) - \vec{\nabla} \times \vec{\nabla} \times \vec{C} + k^2 \vec{C} = \vec{0}$

$$\vec{L} = \vec{\nabla} \psi \quad \vec{M} = \vec{\nabla} \times \psi \vec{a} = \vec{L} \times \vec{a} \quad \vec{N} = \frac{1}{k} \vec{\nabla} \times \vec{M}$$

Problem! $\vec{a}$ must be a constant vector and then $\vec{M}$ and $\vec{N}$ will never be purely normal or tangential over the entire surface of spheres centered at the origin: not good to write boundary conditions in spherically symmetric problems! We would need $\vec{a} \parallel \vec{e}_r$
Fortunately, it turns out to be possible to construct $\vec{M}$ and $\vec{N}$ as

$$\vec{L} = \vec{\nabla} \psi \quad \vec{M} = \vec{\nabla} \times \vec{r} \psi = \vec{L} \times \vec{r} \quad \vec{N} = \frac{1}{k} \vec{\nabla} \times \vec{M}$$

Proof: Let us try to find a solution of $\vec{\nabla}(\vec{\nabla} \cdot \vec{C}) - \vec{\nabla} \times \vec{\nabla} \times \vec{C} + k_0^2 \vec{C} = \vec{0}$
 in the form $\vec{M} = \vec{\nabla} \times (u(r) \vec{e}_r \psi) = \vec{L} \times u(r) \vec{e}_r + \psi \vec{\nabla} \times u(r) \vec{e}_r$

Since $\vec{L} = \vec{\nabla} \psi = \frac{\partial \psi}{\partial r} \vec{e}_r + \frac{1}{r} \frac{\partial \psi}{\partial \theta} \vec{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \varphi} \vec{e}_\varphi$

$$\vec{M} = \begin{pmatrix} \frac{\partial \psi}{\partial r} \\ \frac{1}{r} \frac{\partial \psi}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \varphi} \end{pmatrix} \times \begin{pmatrix} u(r) \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \varphi} u(r) \\ -\frac{1}{r} \frac{\partial \psi}{\partial \theta} u(r) \end{pmatrix}$$

$$\Rightarrow \vec{M} = \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} (u \psi) \vec{e}_\theta - \frac{1}{r} \frac{\partial}{\partial \theta} (u \psi) \vec{e}_\varphi$$

$$\vec{\nabla} \cdot \vec{M} = 0$$

$\vec{\nabla} \times \vec{\nabla} \times \vec{M} - k^2 \vec{M}$ can be expressed in spherical coordinates (exercise). The $\vec{e}_r$ component is 0 and the $\vec{e}_\theta$ and $\vec{e}_\varphi$ components are identical and satisfied only if $u(r) = r$. QED

We therefore have:

$$\vec{M} = \frac{1}{\sin \theta} \frac{\partial \psi}{\partial \varphi} \vec{e}_\theta - \frac{\partial \psi}{\partial \theta} \vec{e}_\varphi$$

$$\vec{N} = \left[\frac{1}{k} \frac{\partial^2 (r \psi)}{\partial r^2} + k r \psi \right] \vec{e}_r + \frac{1}{k r} \frac{\partial^2 (r \psi)}{\partial r \partial \theta} \vec{e}_\theta + \frac{1}{k r \sin \theta} \frac{\partial^2 (r \psi)}{\partial r \partial \varphi} \vec{e}_\varphi$$

[Proof: Exercise]

Since $\psi = f_1(r) f_2(\theta) f_3(\varphi)$ is such that f_1 (and hence ψ) satisfies

$$r^2 \frac{d^2 f_1}{dr^2} + 2r \frac{df_1}{dr} + (k^2 r^2 - m(m+1)) f_1 = 0$$

[eq (1) in the note on scalar spherical waves]

the radial component of $\vec{N}$, $N_r = \frac{1}{k} \frac{\partial(r\psi)}{\partial r^2} + k^2 r \psi$, reduces to

$$N_r = \frac{m(m+1)}{kr} \psi$$

proof : exercise

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Carrying out the differentiation for $f_{\theta mm}$ and $f_{\varphi mm}$, we get

$$\vec{M}_{\theta mm} = \left[-\frac{m}{\sin\theta} z_m(kr) P_m^m(\cos\theta) \frac{\sin(m\varphi)}{\cos(m\varphi)} \right] \vec{e}_\theta$$

$$- \left[z_m(kr) \frac{\partial}{\partial\theta} P_m^m(\cos\theta) \frac{\cos(m\varphi)}{\sin(m\varphi)} \right] \vec{e}_\varphi$$

$$\vec{N}_{\theta mm} = \left[\frac{m(m+1)}{kr} z_m(kr) P_m^m(\cos\theta) \frac{\cos(m\varphi)}{\sin(m\varphi)} \right] \vec{e}_r$$

$$+ \left[\frac{1}{kr} \frac{\partial}{\partial r} [r z_m(kr)] \frac{\partial}{\partial\theta} P_m^m(\cos\theta) \frac{\cos(m\varphi)}{\sin(m\varphi)} \right] \vec{e}_\theta$$

$$+ \left[\frac{m}{kr \sin\theta} \frac{\partial}{\partial r} [r z_m(kr)] P_m^m(\cos\theta) \frac{\sin(m\varphi)}{\cos(m\varphi)} \right] \vec{e}_\varphi$$

$$\vec{L}_{\theta mm} = \left[\frac{\partial}{\partial r} z_m(kr) P_m^m(\cos\theta) \frac{\cos(m\varphi)}{\sin(m\varphi)} \right] \vec{e}_r$$

$$+ \left[\frac{1}{r} z_m(kr) \frac{\partial}{\partial\theta} P_m^m(\cos\theta) \frac{\cos(m\varphi)}{\sin(m\varphi)} \right] \vec{e}_\theta$$

$$+ \left[\frac{m}{r \sin\theta} z_m(kr) P_m^m(\cos\theta) \frac{\sin(m\varphi)}{\cos(m\varphi)} \right] \vec{e}_\varphi$$

2. Orthogonality relations

We integrate over a sphere of radius r the scalar product between two spherical vector field solutions. $\vec{L} \cdot \vec{M}$ & $\vec{H} \cdot \vec{N}$ always orthogonal, same with even/odd, $m \neq m'$ or $m \neq m'$ combinations. The only non-zero scalar products are:

$$\int_0^{2\pi} \int_0^\pi \vec{L}_{e,mm} \cdot \vec{L}_{e,mm} \sin\theta d\theta d\varphi = (1+\delta) \frac{2\pi}{(2m+1)^2} \frac{(m+m)!}{(m-m)!} k^2 \left\{ m \left[z_{m-1}(kr) \right]^2 + (m+1) \left[z_{m+1}(kr) \right]^2 \right\}$$

$$\int_0^{2\pi} \int_0^\pi \vec{M}_{e,mm} \cdot \vec{M}_{e,mm} \sin\theta d\theta d\varphi = (1+\delta) \frac{2\pi}{2m+1} \frac{(m+m)!}{(m-m)!} m(m+1) \left[z_m(kr) \right]^2$$

$$\int_0^{2\pi} \int_0^\pi \vec{N}_{e,mm} \cdot \vec{N}_{e,mm} \sin\theta d\theta d\varphi = (1+\delta) \frac{2\pi}{(2m+1)^2} \frac{(m+m)!}{(m-m)!} m(m+1) \left\{ (m+1) \left[z_{m-1}(kr) \right]^2 + m \left[z_{m+1}(kr) \right]^2 \right\}$$

$$\int_0^{2\pi} \int_0^\pi \vec{L}_{e,mm} \cdot \vec{N}_{e,mm} \sin\theta d\theta d\varphi = (1+\delta) \frac{2\pi}{(2m+1)^2} \frac{(m+m)!}{(m-m)!} m(m+1) k \left\{ \left[z_{m-1}(kr) \right]^2 - \left[z_{m+1}(kr) \right]^2 \right\}$$

with $\delta = 0$ if $m > 0$ and $\delta = 1$ if $m = 0$

3. Vector plane wave expansion

Let $\vec{f}(z)$ be a plane wave propagating along z and linearly polarized along $\vec{a} = \vec{e}_x, \vec{e}_y$ or $\vec{e}_z$.

$$\vec{f}(z) = \vec{a} e^{-jkz} = \vec{a} e^{-jk r \cos \theta}$$

We have:

$$\vec{e}_x e^{-jkz} = \sum_{n=1}^{+\infty} (-j)^n \frac{2n+1}{n(n+1)} [\vec{M}_{o1n} + j \vec{N}_{e1n}]$$

$$\vec{e}_y e^{-jkz} = - \sum_{n=1}^{+\infty} (-j)^n \frac{2n+1}{n(n+1)} [\vec{M}_{e1n} - j \vec{N}_{o1n}]$$

$$\vec{e}_z e^{-jkz} = \frac{1}{k} \sum_{n=0}^{+\infty} (-j)^{n-1} (2n+1) \vec{L}_{e0n}$$

where $\vec{M}, \vec{N}, \vec{L}$ are built from $z_m = j_m$

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